

# **Optimization of Type-2 Fuzzy Systems: Theory and Applications**

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**Abstract:** Type-2 fuzzy systems are powerful intelligent models based on the theory of fuzzy sets, originally proposed by Prof. Zadeh. Most real-world applications up to now are based on type-1 fuzzy systems, which are built based on the original (type-1) fuzzy sets that extend the concept of classical sets. Type-2 fuzzy sets extend type-1 fuzzy sets by allowing the membership to be fuzzy, in this way allowing a higher level of uncertainty management. Even with the current successful applications of type-1 fuzzy systems, now several papers have shown that type-2 is able to outperform type-1 in control, pattern recognition, manufacturing and other areas. The key challenge in dealing with type-2 fuzzy models is that their design has a higher level of complexity, and in this regard the use of bio-inspired optimization techniques is of great help in finding the optimal structure and parameters of the type-2 fuzzy systems for particular applications, like in control, robotics, manufacturing and others. Methodologies for designing type-2 fuzzy systems using bio-inspired optimization in different areas of application are presented as illustration. In particular, we will cover Bee Colony Optimization, Particle Swarm Optimization, Gravitational Search and similar approaches to the optimization of fuzzy systems in control applications, robotics and pattern recognition. We will also consider using fuzzy logic for enhancing the performance of metaheuristics, where also good results have been achieved. Finally, the prospects for the future applications of type-3 fuzzy logic will be discussed.